An Unconditionally Secure Key Management Scheme for Large-Scale Heterogeneous Wireless Sensor Networks

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Abstract—Key establishment in sensor networks becomes a challenging problem because of the resource limitations of the sensors and also due to vulnerability to physical capture of the sensor nodes. In this paper, we propose an unconditionally secure probabilistic group-based key pre-distribution scheme for a heterogeneous wireless sensor network. The proposed scheme always guarantees that no matter how many sensor nodes are compromised, the non-compromised nodes can still communicate with 100% secrecy, i.e., the proposed scheme is always unconditionally secure against node capture attacks. Moreover, it provides significantly better trade-off between communication overhead, computational overhead, network connectivity and security against node capture as compared to the existing key pre-distribution schemes. It also supports dynamic node addition after the initial deployment of the nodes in the network.

Keywords: Key management; Key pre-distribution; Security; Polynomial-based key distribution; Random pairwise keys scheme; Large-scale heterogeneous sensor networks.

I. INTRODUCTION

In a wireless sensor network a large number of tiny computing nodes, called sensors, are deployed for the purpose of sensing data and then to bring the data back securely to nearby base stations. The base stations then preform the costly computation on behalf of the sensors to analyze the data sensed by the sensors. Due to resource limitations of the nodes and also due to the vulnerability of physical captures of the nodes, the traditional public key cryptographic techniques such as RSA [1], Diffie-Hellman key exchange [2], El Gamal cryptosystem [3], etc. are too much complicated and energy consuming. The symmetric ciphers such as DES, AES, RC5 [4], [5] are then the viable options for encrypting/decrypting secret data. In order to use symmetric cipher, we need to establish pairwise keys between communicating sensors. But setting up symmetric keys among communicating nodes remains till now a challenging problem. A survey on sensor networks can be found in [6].

In order to establish pairwise keys between neighboring sensor nodes, a protocol is used known as the *bootstrapping protocol*. A bootstrapping protocol has the following three phases, called the *key pre-distribution phase*, the *direct key* establishment (shared key discovery) phase and the path key establishment phase. Before deployment of nodes in a target field, the key setup server (usually the base station) performs the key pre-distribution phase. In this phase each sensor node is loaded by a set of pre-distributed keys in its memory. The next phase occurs immediately after deployment of nodes in the target field. After deployment, the direct key establishment phase is performed by nodes in order to establish direct pairwise keys between them. To establish pairwise keys between nodes, each node first discovers its neighbor nodes in its communication range. Two nodes u and v are called *physical* neighbors if they are within communication ranges of one another. In order to discover physical neighbors, each node broadcasts a HELLO message containing its own ID. Thus, each node also receives HELLO message from its neighbor nodes. In this way, each node prepares a list of neighbor nodes which are basically the physical neighbors. Two physical neighbors u and v are called key neighbors if they share one or more key(s) in their key rings pre-loaded before deployment during the key pre-distribution phase. Finally, nodes u and v can secretly and directly communicate with one another if and only if they are both physical and key neighbors. In this case nodes u and v are termed as *direct neighbors*. The final phase known as the path key establishment phase is an optional stage and, if executed, adds to the connectivity of the network. Suppose two physical neighbors u and v could not able to establish a pairwise key during the direct key establishment phase because of the fact that they do not share any common key(s) in their key rings. In this phase, a secure path is discovered between u and v and a fresh pairwise key k is sent securely along that path. Thus, nodes u and v use this path key k for their future secret communications.

Several symmetric key pre-distribution techniques [7], [8], [9], [10], [11], [12], [13], [14] are proposed in the literature. Most of these schemes are not scalable and also they are vulnerable to a small number of captured nodes in the network. In this paper, we propose a probabilistic group-based key pre-distribution scheme based on a heterogeneous wireless sensor network (HWSN). Our scheme makes use of pre-deployment

locations of sensors in order to significantly enhance network performances as compared to those for the existing key predistribution schemes.

The rest of the paper is organized as follows. Section II describes briefly the related works. In Section III, we introduce our proposed scheme which is a probabilistic group-based key distribution scheme applied in a heterogeneous wireless sensor network. Section IV gives performance analysis and security analysis of our scheme. Section V discusses the simulation results of our scheme. In Section VI, we compare the performances of our scheme with the existing related schemes. Finally, we conclude the paper in Section VII.

II. RELATED WORK

Eschenauer and Gligor in 2002 first proposed a random key pre-distribution scheme [7]. Their scheme, henceforth referred to as the EG scheme, consists the following three phases. In the key pre-distribution phase, the (key) setup server chooses a pool \mathcal{K} of M randomly generated symmetric keys. Each key is assigned a unique identifier in the pool \mathcal{K} . For each sensor node u to be deployed, the setup server picks a random subset K_u of size m from the pool \mathcal{K} and loads this subset into its memory. This subset K_u is called the key ring of the node u. After the sensor nodes are deployed in some target field, a *direct key establishment phase* (also called the shared key discovery phase) is performed by each sensor node in the network. To establish a secret key between them, they exchange the key ids from their key rings in plaintext. If there is a common key id between their key rings, the corresponding key is taken as the secret key between them and they use this key for their future secure communication. Nodes which discover that they have a shared secret key in their key rings then verify that their neighbor actually holds the key through a challenge-response protocol. Since the random subsets for the nodes are drawn from the pool \mathcal{K} randomly without replacement, the same key may be used for secret communication by several pairs of neighbor nodes in the network. The *path key establishment phase* is an optional stage, and if executed, adds to the connectivity of the network. Suppose two neighbor nodes u and v fail to establish a secret key between them in the direct key establishment phase, but there exists a secure path. Once such a secure path is discovered, u generates a new random key k and securely transmits it along this path to the desired destination node v. In this way, u and v can communicate secretly and directly using k. However, the main problem is that the communication overhead increases significantly with the number h of hops. For this reason, in practice, h is restricted to a small value, say 2 or 3. An improvement of the path key establishment phase has been proposed in [15], called the key reshuffling scheme, which improves the network performances significantly as compared to those for the path key establishment phase.

The q-composite scheme proposed by Chan et al. [8] is one of the modifications of the EG scheme. In this scheme, two neighbor nodes require at least q common keys (q > 1) instead of one in order to establish a secret key between them. The *q*-composite scheme enhances the security against node capture significantly as compared to that for the EG scheme if the number of captured nodes is small.

In the multipath key reinforcement scheme proposed by Chan et al. [8], the main idea is to strengthen the security of an established link key by establishing the link key through multiple paths. This method can be applied in conjunction with the EG scheme to yield greatly improved resilience against node capture attacks by trading off some network communication overhead.

The random pairwise keys scheme proposed by Chan et al. [8] is described as follows. Let m be the size of the key ring of each sensor node and p the probability that any two nodes be able to communicate securely. In the key predistribution phase, a total of $n = \frac{m}{n}$ unique node identifiers are generated. The actual size of the network may be smaller than n. For each sensor node to be deployed, a set of m other randomly distinct node ids is selected and then a pairwise key is generated for each pair of nodes. The key is stored in both nodes' key rings along with the id of the other node that also knows the key. In the direct key establishment phase, each node broadcasts its own id to its neighbor nodes in its communication range. Two neighbor nodes can then easily verify the id of a neighbor node in their key rings. If the id of a neighbor node is found in a node's key ring, they share a common pairwise key for communication. A cryptographic handshake is then performed between neighbor nodes for mutual verification of the common key. Since the pairwise key between the two nodes is generated randomly, no matter how many nodes are captured by an adversary, the other non-compromised nodes communicate with each other with 100% secrecy. Thus, the random pairwise keys scheme provides unconditional security against node capture attacks. However, this scheme degrades network connectivity when the network size is large.

The polynomial-based key pre-distribution scheme proposed by Blundo et al. in [16] is described as follows. In the key predistribution phase, an offline key setup server assigns unique identifiers to all the sensor nodes to be deployed in a target field. The setup server then generates randomly a t-degree symmetric bivariate polynomial f(x, y), defined by f(x, y) = $\sum_{i,j=0}^{t} a_{ij} x^i y^j$, where the coefficients $a_{ij} (0 \le i, j \le t)$ are randomly chosen from a finite field $F_q = GF(q)$, q is a prime that is large enough to accommodate a symmetric cryptographic key, with the property that f(x, y) = f(y, x). For each sensor node u to be deployed, the setup server computes a polynomial share f(u, y). We note that f(u, y)is a t-degree univariate polynomial. The setup server finally loads the coefficients of y^j of f(u, y) in the memory of the sensor node u. In the direct key establishment phase, each sensor node u first locates its physical neighbors in its communication range and broadcasts its own id to its neighbors. Let u and v be two neighbors. After receiving the id of the node v, u computes the secret key shared with v as $k_{u,v} = f(u, v)$. Similarly, v computes the secret key shared

with u as $k_{v,u} = f(v, u)$. Since f(u, v) = f(v, u), we have $k_{u,v} = k_{v,u}$. Thus, both the nodes u and v store the key $k_{u,v}$ for their future secret communication. The advantage of this scheme is that any two neighbor nodes can establish a secret key using the same symmetric bivariate polynomial f(x, y), and there is no communication overhead during the pairwise key establishment process. The main drawback is that if more than t nodes in the network are compromised by an adversary, he/she can easily reconstruct the original polynomial using Lagrange interpolation [17]. As a result, all the pairwise keys shared between the non-compromised nodes will also be compromised. Thus, this scheme is unconditionally secure and t-collusion resistant. Although increasing the value of t can improve the security property of this scheme, it is not feasible for wireless sensor networks due to the limited memory in sensors.

Liu and Ning's polynomial-pool based key predistribution scheme [18] improves security considerably as compared to that for the polynomial-based key pre-distribution scheme, the EG scheme, and the q-composite scheme. The locationaware closest pairwise keys scheme (CPKS) based on the random pairwise keys scheme and closest polynomials predistribution scheme (CPPS) based on the polynomial-pool based scheme [12] improve significantly the performances of network connectivity and resilience against node capture when the deployment error between the actual location and the expected deployed location of sensor nodes is smaller. The group-based key pre-distribution scheme proposed by Huang et al. [19] is a matrix based key distribution scheme. Their scheme requires less number of keys preinstalled for each sensor and is resilient to selective node capture attack and node fabrication attack. Liu and Ning proposed a group based key pre-distribution scheme [20] which performs better than the existing schemes [7], [8], [9]. The deterministic group based key pre-distribution scheme proposed in [21] improves significantly better performances as compared to other existing key pre-distribution schemes [7], [8], [9], [12], [13], [14].

The low-energy key management scheme (LEKM) [13] and improved key distribution mechanism (IKDM) [14] are proposed in hierarchical WSNs. These schemes have better performances than the random key distribution schemes [7], [8], because hierarchical structure has used for those schemes. LEKM requires less key storage overhead than the random schemes [7], [8]. The main drawback of LEKM is that once a cluster head in a cluster is captured, all the keys in sensors of that cluster are compromised. Though IKDM requires only two secret keys to be stored in each sensor's memory, once a cluster head in a cluster is captured after the network initialization phase, all the keys stored in sensors in that cluster are compromised. The basic problem in LEKM and IKDM is that all the sensors in a cluster communicate directly with the cluster head only.

III. THE PROPOSED SCHEME

In this section, we first describe in brief the network model used for developing our scheme. We then describe the main motivation behind development of our scheme. Finally, we describe our proposed scheme.

A. Network Model

In this section, we discuss a heterogeneous network model which will be used for development of our proposed scheme.

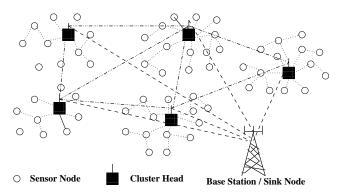


Fig. 1. A heterogeneous wireless sensor network (HWSN) architecture.

A heterogeneous wireless sensor network (HWSN) is shown in Figure 1. From this figure, we see that there is a hierarchy among the nodes based on their capabilities: base station, cluster heads and sensor nodes. Sensor nodes are inexpensive, limited capability and generic wireless devices. Each sensor has limited battery power, memory size and data processing capability and short radio transmission range. Sensor nodes in a group (also called a cluster) communicate among each other in that cluster and finally communicate with the cluster head (CH). *Cluster heads* have more resources than sensors. They are equipped with high power batteries, larger memory storage, powerful antenna and data processing capabilities. Cluster heads can execute relatively complicated numerical operations than sensors and have much larger radio transmission range. Cluster heads can communicate with each other directly and relay data between its cluster members and the base station. A base station or sink node (BS) is typically a gateway to another network, a powerful data processing/storage center, or an access point for human interface. A base station collects sensor readings, performs costly operations on behalf of sensor nodes and manages the network. In some applications, the base station is assumed to be trusted. Thus, the base station is used as key distribution center (KDC).

Sensor nodes are deployed around one or more hop neighborhood of the base station. Since the base station is most powerful node in the network, it can reach all the sensor nodes in that network. Depending on the applications, the base station (BS) can be located either in the center or at a corner of the network. Data flow in such networks can be: (i) pairwise (unicast) among sensor nodes, (ii) group-wise (multicast) within a cluster of sensor nodes, and (iii) network-wise (broadcast) from base station to sensor nodes.

B. Motivation

Our scheme is motivated by the followings. In many sensing applications, connectivity between all sensor nodes is not necessary. Thus, data centric mechanism should be performed to aggregate redundant data in order to reduce the energy consumption and traffic load in wireless sensor networks. Therefore, the heterogeneous network model has more operational advantages over the distributed homogeneous model for wireless sensor networks due to inherent limitations of sensors on power and processing capabilities.

The random pairwise keys scheme [8] has the following limitations. Though this scheme always provides unconditional security against node capture, it provides very low network connectivity in particularly when the network size is large. In practice, the sensor network is assumed to be highly scalable and hence the random pairwise keys scheme is not applicable in large-scale distributed sensor networks.

The group-based deterministic key distribution mechanism [21] based on bivariate polynomials provides very high network connectivity and unconditional security against node capture. But this scheme requires computational overhead due to evaluation of a *t*-degree polynomial over a finite field F_q . In this paper, we propose an energy efficient key distribution scheme. Our scheme is an improved version of this groupbased deterministic key distribution mechanism [21] based a heterogeneous network model (as shown in Figure 1) which requires significantly low computational and communication overheads in order to establish pairwise secret keys between communicating nodes in a sensor network.

C. Our approach

As in [21], we consider a heterogeneous wireless sensor network (HWSN) consisting of two types of sensors: a small number of powerful High-end sensors (H-sensors) and a large number of resource-constrained Low-end sensors (L-sensors). H-sensors can execute relatively complicated numerical operations than L-sensors and have much larger radio transmission range and larger storage space than L-sensor nodes. On the other hand, L-sensors are extremely resource-constrained. For example, the H-sensors can be PDAs and the L-sensors are the MICA2-DOT motes [22]. We also assume that the target field is two dimensional and partitioned into a number l of equal sized disjoint groups (clusters). Each group will consist of a group head GH_i (here it is an H-sensor node) and a number n_i of L-sensor nodes. The number n_i of regular sensor nodes is to be taken in each deployment group so that the network connectivity in each group is reasonably high. L-sensors are to be deployed randomly in a group only and each group head will be deployed in that group around the center of that group. For our sake of simplicity, we call an L-sensor node as regular sensor node. The base station (BS) can be located either in the center or at a corner of the network.

The following assumptions are made while constructing our protocol.

- After deployment of the nodes in a target field, each Lsensor (regular sensor node) as well as H-sensor nodes (group heads) are assumed to be static only.
- Base station is assumed to be trusted and it will never be compromised by an attacker.
- An adversary can eavesdrop on all traffic, inject packets and reply old messages previously delivered. If an adversary captures a node, all the keying information it holds will also be compromised.

Our scheme makes use of the existing polynomial-based key pre-distribution scheme in order to establish pairwise keys among group heads in a sensor network. We use the extended version of the random pairwise keys scheme in order to facilitate establishment of pairwise keys among regular sensor nodes in a group.

Our scheme consists of the following phases.

1) Key pre-distribution phase: This phase is performed by the (key) setup server in offline before deployment of the sensor nodes in a target field. The steps involved in this phase are as follows:

- Step-1: The setup server first assigns a unique identifier, say id_{GH_i} to each group head GH_i which will be deployed in the target field. For each deployed regular sensor node u, the setup server also assigns a unique identifier, say id_u .
- Step-2: The setup server then selects randomly a unique master key, say MK_{GH_i} for each group head GH_i . This master key is shared between the group head GH_i and the base station only. The setup server also assigns for each deployed regular sensor node u a unique randomly generated master key, say MK_u which is shared with the base station only.
- Step-3: For each deployment group G_i , the setup server generates a node pool, say N_i consisting of the IDs of the group head GH_i and the n_i regular sensor nodes to be deployed in that group.
- Step-4: For each deployed regular sensor node u in each group G_i, the setup server selects a set S_i consisting of randomly chosen m node IDs from the corresponding node pool N_i of that group G_i. Let the set S_i be as S_i = {idv₁, idv₂,..., idv_m}. We note that one of the IDs in S_i may be the ID of the group head GH_i. Then for each pair (u, v_j), (j = 1, 2, ..., m), the setup server computes the m key-plus-id combinations, say {(SK_{u,v_j}, idv_j), j = 1, 2, ..., m}, where SK_{u,v_j} = PRF_{MKv_j}(idu). Here PRF is a pseudo random function proposed by Goldreich et al. [23].
- Step-5: For all the *m* deployed group heads GH_i (i = 1, 2, ..., m), the setup server randomly generates a *t*-degree bivariate polynomial $f(x, y) \in F_q[x, y]$ over a finite field F_q , with the property that f(x, y) = f(y, x), that is, f(x, y) is symmetric such that t >> l. The reason for choosing the degree of the polynomial f(x, y) to be higher is that even if an adversary captures all the l

group heads in the network, the polynomial f(x, y) will never be compromised. The setup server then computes a polynomial share $f(id_{GH_i}, y)$ for each deployed group head GH_i (i = 1, 2, ..., m).

- Step-6: Since the group heads are H-sensors and are more powerful nodes than regular sensor nodes, we can store more keying information in their memory. For each deployed group head GH_i (i = 1, 2, ..., l), the setup server randomly selects a set S = {id_{w1}, id_{w2}, ..., id_{wm'}} from the node pool N_i corresponding to that group G_i, where m' ≥ m. Then for each pair (GH_i, w_j), (j = 1, 2, ..., m'), the setup server also computes the m' key-plus-id combinations, say {(SK_{GH_i,w_j}, id_{w_j}), j = 1, 2, ..., m'}, where SK_{GH_i,w_j} = PRF_{MK_{wi}} (id_{GH_i}).
- Step-7: Finally, the setup server loads the following information into the memory of each group head GH_i (i = 1, 2, ..., l): (i) its own identifier, (ii) its own master key MK_{GHi}, (iii) the polynomial share f(id_{GHi}, y) computed in step-5, and (iv) m' key-plus-id combinations computed in step-6. Each deployed regular sensor node u in the deployment group G_i is loaded with the following information: (i) its own identifier, (ii) its own master key MK_u, and (iii) m key-plus-id combinations computed in step-4. The loaded information in each regular sensor node as well as group head are shown in Tables I and II.

TABLE I Key ring of a regular sensor node u in its deployment group G_i

| id_u |
|--|
| MK_u |
| $\{(SK_{u,v_j}, id_{v_j}), j = 1, 2, \dots, m\},\$ |
| $SK_{u,v_j} = PRF_{MK_{v_j}}(id_u)$ |

TABLE II Key ring of a group head GH_i in its deployment group G_i

| id_{GH_i} |
|--|
| MK_{GH_i} |
| $f(id_{GH_i}, y)$ |
| $\{(SK_{GH_i,w_j}, id_{w_j}), j = 1, 2, \dots, m'\},\$ |
| $SK_{GH_i,w_j} = PRF_{MK_{w_j}}(id_{GH_i})$ |

We note that a typical regular sensor node can store 200 keys in its memory. Hence we take the value of m as m = 200, whereas the value of m' will be taken larger than m due to large storage memory of group heads.

2) Direct key establishment phase: As soon as regular sensor nodes are deployed randomly in their respective groups, their first task is to locate the physical neighbors within their communication ranges. Group heads in their groups locate their physical neighbors which are the regular sensor nodes. Group heads also locate their other group heads in their communication ranges in the network.

In our direct key establishment phase, we have the following two pairwise key establishment procedures: one is

the inter-group pairwise key establishment and other is the intra-group pairwise key establishment. In the inter-group pairwise key establishment, only group heads will establish pairwise secret keys with their neighbor group heads. On the other hand, during the intra-group pairwise key establishment the regular sensor nodes will establish pairwise keys with their neighbor nodes in their own deployment group, and also the group heads will establish pairwise keys with their neighbor regular sensor nodes in their own deployment group.

(a) Inter-group pairwise key establishment

If GH_i and GH_j be two neighbor group heads, they can establish pairwise secret key by exchanging their own ids id_{GH_i} and id_{GH_j} . After exchanging their ids, GH_i computes the pairwise secret key as $f(id_{GH_i}, id_{GH_j})$ by just evaluating its own polynomial share $f(id_{GH_i}, y)$ at the point $y = id_{GH_j}$. In a similar fashion, GH_j computes a secret key $f(id_{GH_j}, id_{GH_i})$ by evaluating its polynomial share $f(id_{GH_j}, y)$ at the point $y = id_{GH_i}$. Since the polynomial is symmetric, so the shared secret key between the group heads GH_i and GH_j is $SK_{GH_i,GH_j} = f(id_{GH_i}, id_{GH_j})$. Finally, they store this key SK_{GH_i,GH_j} for their future secure communication.

(b) Intra-group pairwise key establishment

In this phase, we consider the following three cases:

Case I: regular node to regular node key establishment

In order to establish a secret pairwise key between two neighbor regular sensor nodes, say u and v in a deployment group G_i , they exchange their own ids id_u and id_v . Let the ID of node v be resident in the key ring of node u. Then from Table I, we note that u is sharing a pairwise key with node v. Node u then informs node v that it is sharing a pairwise key $SK_{u,v}$. This notification contains the ID of node u with a small request message. It is noted that this notification never contains the exact key $SK_{u,v}$. After receiving the request from u, node v can easily compute the same pairwise key $SK_{u,v}$ by computing PRF function with the help of its own master key MK_v and the ID of node u as $SK_{u,v}$ $= PRF_{MK_v}(id_u)$. Node v then stores this key $SK_{u,v}$ for future secret communication with the node u.

Case II: group head to regular node key establishment

In order to establish a secret key between a regular sensor node u and its group head GH_i which is within its communication range, they need to exchange their own ids. If the ID of node u is resident in the key ring of the group head GH_i , then it informs to u that it has a pairwise key shared with u. This is done by sending a short notification containing the ID of GH_i to node u. After receiving this notification, u can easily compute the shared secret pairwise key with GH_i as $SK_{GH_i,u} = PRF_{MK_u}(id_{GH_i})$ and store this key for future communication with GH_i . Now, if the ID of u is not resident in the key ring of GH_i , it is also possible that the ID of GH_i is resident in the key ring of node u. In this case, u sends a short notification containing its own ID to group head GH_i . Then GH_i computes the shared secret pairwise key $SK_{GH_i,u}$ with u as $SK_{GH_i,u} = PRF_{MK_{GH_i}}(id_u)$ using its own master key and the ID of node u. GH_i then stores this key for future secret communication with node u.

Case III: regular node to regular node key establishment with help of another group head

This is a spacial case considered here. Assume that a regular node was supposed to be deployed in its group G_i . But due to some deployment error during deployment, it is deployed to some other group, say G_j . It is then noted that u could not able to establish secret keys with its neighbor regular nodes in that group because it does not have any keying information containing in that group. Therefore, we need for the node u to establish pairwise keys with its neighbor nodes with the help of the group head GH_j in G_j as follows (as in [21]).

In order to establish a pairwise key between u and its neighbor node v, node u sends a request containing of its own id id_u and a randomly generated nonce RN_u . After receiving such a request, node v generates a random nonce RN_v and sends a request consisting of its own id id_v as well as the id of u, id_u , random nonces RN_u and RN_v to its own group head GH_i which is protected by its own master key MK_v . Then the group head GH_i forwards this request to its neighbor group head and finally this request comes eventually to the base station. The base station first validates this request by decrypting the request by the master key MK_v of the node v, because the base station has the master key MK_v of v. If the validation passes, the base station then only generates a secret random key $k_{u,v}$ to be shared by the nodes u and v. Then it makes two protected copies: one for node u, $E_{MK_u}(k_{u,v} \oplus id_u \oplus RN_u)$ and other for node v, $E_{MK_v}(k_{u,v} \oplus id_v \oplus RN_v)$ where $E_k(M)$ denotes the encryption of data M using the key k. The first one is sent to node u and the later copy is sent to node v via group heads. Nodes u and v first decrypt their protected copies. Node u retrieves the secret key $k_{u,v}$ using its own id and its own random nonce RN_u as $k_{u,v} = (k_{u,v} \oplus id_u \oplus RN_u)$ $\oplus(id_u \oplus RN_u)$. Similarly, node v also uses its own id and random nonce RN_v in order to retrieve the secret key $k_{u,v}$ as $k_{u,v} = (k_{u,v} \oplus id_v \oplus RN_v) \oplus (id_v \oplus RN_v)$. We also note that the communication overhead is not much due to involvement of the group heads during this process. In fact, such a scenario is unlikely to occur, because the probability of having a smaller deployment error is typically higher than the probability of having a larger one when the nodes are randomly deployed in a deployment group. In a similar fashion, node u can also establish a secret key with the group head GH_j if GH_j is neighbor of u.

3) Dynamic sensor node addition phase: In order to add a new regular sensor node u in a particular deployment group, say GH_i , the key setup server assigns a unique id, say id_u and randomly generates a master key MK_u for u which will be shared with the base station only. Then the setup server selects a set S_i consisting of randomly chosen m node IDs from the corresponding node pool N_i of that group G_i . Let the set S_i be as $S_i = \{id_{v_1}, id_{v_2}, \ldots, id_{v_m}\}$. We note that one of the IDs in S_i may be the ID of the group head GH_i . Then for each pair $(u, v_j), (j = 1, 2, \ldots, m)$, the setup server computes the m key-plus-id combinations, say $\{(SK_{u,v_j}, id_{v_j}), j =$ $1, 2, \ldots, m\}$, where $SK_{u,v_j} = PRF_{MK_{v_j}}(id_u)$ and loads these information in its memory.

After deployment in its own deployment group, it establishes secret keys with its neighbor nodes within its group as described in the *intra-group pairwise key establishment phase*.

4) Dynamic group-head addition phase: We now consider that a group head GH_i in a group G_i is captured by an adversary. Thus, we need to add a new group head, say, GH'_i in that group G_i in order to replace that node GH_i . In order to add the group head GH'_i , the setup server assigns a unique id, say $id_{GH'_{+}}$ and a randomly generated master key $MK_{GH'_{+}}$ which will be shared with the base station only. The setup server then randomly selects a set $S = \{id_{w_1}, id_{w_2}, \dots, id_{w_{m'}}\}$ from the node pool N_i corresponding to that group G_i , where $m' \geq m$. Then for each pair (GH'_i, w_j) , $(j = 1, 2, \dots, m')$, the setup server also computes the m' key-plus-id combinations, say $\{(SK_{GH'_{i},w_{j}}, id_{w_{j}}), j = 1, 2, ..., m'\}$, where $SK_{GH'_i,w_j} = PRF_{MK_{w_j}}(id_{GH'_i})$. The setup server loads the following information in its memory: (i) the identifier $id_{GH'_i}$ for GH'_i , (ii) randomly generated master key $MK_{GH'}$, (iii) the polynomial share $f(id_{GH'}, y)$, and (iv) m' key-plus-id combinations as computed above.

After deployment in the group G_i , the group head GH'_i establishes pairwise keys with its neighbor group heads using the *inter-group pairwise key establishment phase* and with the regular sensor nodes using the *intra-group pairwise key establishment phase*.

IV. ANALYSIS OF OUR SCHEME

In this section, we analyze the network connectivity of our scheme which is the probability that any two neighbor nodes in a deployment group can establish a secret pairwise key between them. We then discuss the resilience against node capture of our scheme. Finally, we analyze the overhead requirements for storage, communication and computation for key establishment between two neighbor regular sensor nodes.

A. Network connectivity

From inter-group pairwise key establishment phase described in Section III.C.2, we note that every group head can establish a pairwise secret key with its neighbor group heads in the network using its own polynomial share. Let $p_{grouphead-grouphead}$ denote the probability that a group head can establish a pairwise secret key with its another neighbor group head. Then, we have,

$$p_{grouphead-grouphead} = 1.$$
 (1)

Now, we will concentrate on the network connectivity in each deployment group G_i (i = 1, 2, ..., l). Let us first consider the case where a regular sensor node u can establish a pairwise key with its another neighbor regular sensor node vin their group G_i . From intra-group pairwise key establishment phase described in Section III.C.2, we see that u and v can establish a pairwise key if any one of the following two events occur:

 E_1 : the event that the ID of node u is resident in v's key ring E_2 : the event that the ID of node v is resident in u's key ring

Let p_1 denote the probability that the id of a node will be resident in another node's key ring. Then we have $p_1 = P(E_1) = P(E_2)$. The total number of ways to select m ids from the pool N_i of size $n_i + 1$ is $\binom{n_i+1}{m}$. For a fixed key ring of node u, the total number of ways to select key ring of a node v such that key ring of v does not have the id of u is $\binom{(n_i+1)-1}{m} = \binom{n_i}{m}$. Thus, we have,

$$p_1 = \begin{cases} 1 - \frac{\binom{n_i}{m}}{\binom{n_i+1}{m}} = \frac{m}{n_i+1}, \text{ if } m < n_i + 1. \\ 1, \text{ if } m \ge n_i + 1. \end{cases}$$
(2)

Let $p_{sensor-sensor}$ be the probability that two neighboring regular sensor nodes u and v can establish a pairwise key in a group G_i . Then we have, $p_{sensor-sensor} = 1-$ (probability that none of u and v will establish a pairwise key). Hence,

$$p_{sensor-sensor} = 1 - (1 - p_1)^2.$$
 (3)

We now consider the probability of establishing a pairwise key between a group head GH_i and its neighboring regular sensor node u in a group G_i . Let p_2 be the probability that the id of u will be resident in key ring of GH_i . Then it is easy to deduce (as derived for p_1) that

$$p_2 = \begin{cases} 1 - \frac{\binom{n_i}{m'}}{\binom{n_i+1}{m'}} = \frac{m'}{n_i+1}, \text{ if } m' < n_i + 1. \\ 1, \text{ if } m' \ge n_i + 1. \end{cases}$$
(4)

If $p_{grouphead-sensor}$ represents the probability that a key is established between GH_i and u in group G_i , we have

$$p_{grouphead-sensor} = 1 - (1 - p_1)(1 - p_2).$$
 (5)

Overall network connectivity in a group G_i : We note that each group G_i contains at most n_i regular sensor nodes and a group head GH_i . Thus, $|G_i| = n_i + 1$. Let each node have d average number of neighbor nodes. We consider each group is an undirected graph having $n_i + 1$ nodes, each node having the degree d. Then the total direct communication links in the group becomes the total number of edges in G_i which is equal to $\frac{(n_i+1)d}{2}$. The total number of secure direct links formed in the group G_i by the regular sensor nodes and the group head G_i are $\frac{n_i \times d}{2} \cdot p_{sensor-sensor}$ and $d \cdot p_{grouphead-sensor}$ respectively. Thus, we have $\frac{n_i \times d}{2} \cdot p_{sensor-sensor} + d \cdot p_{grouphead-sensor}$ secure links out of the total $\frac{(n_i+1) \times d}{2}$ direct links. Hence, the

overall network connectivity in G_i can be estimated as

$$p_{overall} = \frac{\frac{n_i \times d}{2} \cdot p_{sensor-sensor} + d \cdot p_{grouphead-sensor}}{((n_i + 1) \times d)/2}$$
$$= \frac{n_i \cdot p_{sensor-sensor} + 2 \cdot p_{grouphead-sensor}}{n_i + 1}.$$
 (6)

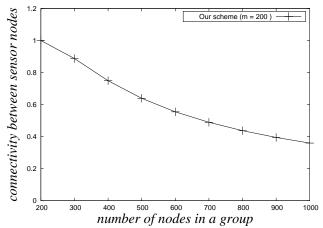


Fig. 2. Number of regular sensor nodes vs. network connectivity between regular sensor nodes in a group G_i , with m = 200.

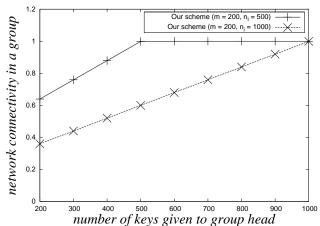


Fig. 3. Network connectivity between a regular sensor node and its group head GH_i in a group G_i , with m = 200, $n_i = 500$, 1000, and different values of m'.

Figure 2 shows the relationship between the network connectivity among regular sensor nodes and the number of nodes in a group. We assume that each regular sensor node is capable of holding 200 cryptographic keys in its memory (i.e., m = 200). It is clear to see from this figure that network connectivity increases when the number of regular sensor nodes in group is smaller. We also note that even if the number of regular sensor nodes reaches 1000, the network connectivity between regular sensor nodes in that group remains high.

Figure 3 illustrates the network connectivity among a group head and its neighbor regular sensor node in a group. Since the group head is powerful node than regular sensors, loading of an excessive amount of keying materials gives very high network connectivity between that group head and its neighbor regular sensor node.

B. Resilience against node capture

The resilience against node capture attack of a key distribution scheme is measured by estimating the fraction of total secure communications that are compromised by a capture of c nodes not including the communication in which the compromised nodes are directly involved. In other words, we want to find out the probability that the adversary can decrypt the secret communications between two non-compromised nodes u and v when c sensor nodes are already compromised.

From our direct key establishment phase, we notice that each group head GH_i is given a *t*-degree polynomial share $f(id_{GH_i}, y)$ for establishing pairwise keys with its neighbor group heads and the degree of this polynomial is greater than the total number of group heads in the network. The pairwise keys established by the group heads are different. Based on the security of the polynomial-based key pre-distribution scheme [16] even if an adversary captures all the group heads, he/she could not able to compromise this polynomial.

Based on the security of the PRF function [23], if a node's master key is not disclosed, no matter how many pairwise keys generated by this master key are disclosed, the task is still computationally difficult for an adversary to recover the master key as well as the non-disclosed pairwise keys generated with different ids of sensor nodes. Since each pre-distributed pairwise key between two regular sensor nodes, and a regular sensor node and its group head are generated using PRF function randomly, no matter how many nodes are captured, the direct pairwise keys between non-captured nodes are still secure. In other words, node compromise does not eventually lead to compromise of direct pairwise keys between other non-captured nodes, that is, any two non-captured neighboring nodes communicate with 100% secrecy. Hence, our scheme is always unconditionally secure against node capture attack.

C. Overheads

In this section, we only consider overheads required by the regular sensor nodes, because they are resource-constrained.

From the key pre-distribution phase (described in Section III.C.1) we see that every regular sensor node requires to store its own master key as well as m key-plus-id combinations in its memory. Thus, the storage overhead is mainly due to storing m + 1 keys.

A regular sensor node in a deployment group needs to exchange a short request message containing its own id with its neighbor node in that group in order to establish a pairwise key between them, if the id of the neighbor node is resident in its key ring. For the special case described in the direct key establishment phase in Section III.C.2, if a regular node which was expected to deploy in a group but during deployment it is deployed in another group, it requires to establish a pairwise key with its neighbor nodes in that group with the help of group heads. Since the probability of having a smaller deployment error is typically higher than the probability of having a larger one when the nodes are randomly deployed in a deployment group, such a situation is unlikely to occur frequently. Thus, the communication overhead is mainly due to transmission of a short request message.

In order to establish a pairwise key, a regular sensor node needs to perform a PRF operation. Zhu et al. [24] pointed out due to the computational efficiency of pseudo random functions, the computational overhead of the PRF function is negligible. Hence, the computational overhead of our scheme is low as compared to that of computation of a *t*-degree polynomial over a finite field F_q as in [16], [25], [21].

V. SIMULATION RESULTS

In this section, we discuss the simulation results of network connectivity in each group.

We have implemented our scheme in C. We have taken a square deployment field for our simulation. The target field is partitioned into l groups G_i (i = 1, 2, ..., l), each of equal size. For each group G_i , we have deployed a group head GH_i around the center of the group. The number n_i of regular sensor nodes is taken to be equal for each group. We deploy the n_i regular sensor nodes randomly in each group G_i . The following parameters are considered for our simulation:

- The number of groups in the target field is l = 100.
- The number of regular sensor nodes deployed in each group is ≤ 1000.
- The area of the deployment field is $A = 1000m \times 1000m$.
- The area of each group is $100m \times 100m$.
- The communication range of each regular sensor node is 30 meters.
- The average number of nodes for each node is ≤ 100 .

We have simulated overall network connectivity for each group and then taken the average overall network connectivity for a group. Figures 4 and 5 show the relationship between the simulated overall network connectivity in a group versus the analytical overall network connectivity in that group, with m = 200, and different values of m'. We observe that both the simulation as well as analysis results tally closely.

VI. COMPARISON WITH PREVIOUS SCHEMES

In this section, we compare security against node capture of our scheme with that for the existing schemes.

The comparison of resilience against sensor node capture between our scheme, the polynomial-based key distribution scheme [16], the polynomial-pool based key distribution scheme [18], the EG scheme [7], the *q*-composite scheme [8], the low-energy key management scheme (LEKM) [13] and the improved key distribution mechanism (IKDM) [14] are shown in Figures 6 and 7. We assume that each sensor node is capable of holding 200 cryptographic keys in its key ring. In LEKM and IKDM, we have taken 100 clusters and we assume that each cluster has 100 sensors, since all the sensors will directly

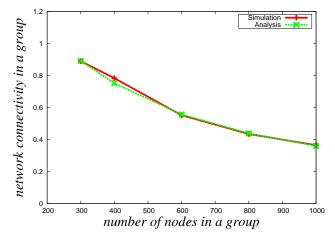


Fig. 4. Average overall network connectivity of a group G_i , with m = 200 and m' = 200.

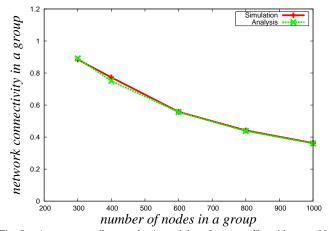


Fig. 5. Average overall network connectivity of a group G_i , with m = 200 and m' = 300.

communicate to their group head only. The network connectivity for all schemes is taken ≈ 1.00 with suitable choice of their respective parameters. We note from these figures that even if the number of captured sensor nodes is small, the EG scheme, the q-composite scheme, the polynomialbased scheme and the polynomial-pool based scheme reveal a large fraction of total secure communication between noncompromised sensor nodes in the network. We also see that our scheme, LEKM and IKDM provide unconditional security against sensor node capture. Since in our scheme a deployment group can have 221 members including a group head (an Hsensor node), our scheme supports large-scale network than LEKM and IKDM with the same number of cluster heads (group heads). As a result, though LEKM and IKDM provide unconditional security against sensor node capture, they can not still support a large network as compared to our scheme with the same number of cluster heads (group heads).

Figure 8 shows the number of compromised sensor keys vs. number of the compromised cluster heads (group heads) during the network initialization phase. In LEKM and IKDM, we assume that there are 100 sensors in each cluster and

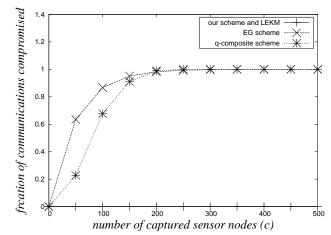


Fig. 6. Comparison of resilience against node capture among our scheme, the EG scheme, the *q*-composite scheme, and LEKM.

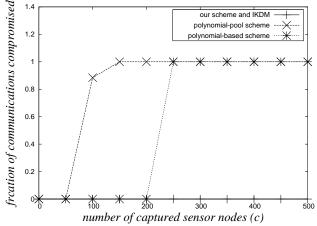


Fig. 7. Comparison of resilience against node capture among our scheme, the polynomial-based scheme, the polynomial-pool based scheme, and IKDM.

100 cluster heads in a network so that they can support 10,000 sensor nodes. In these schemes, all the sensor nodes will communicate with the cluster head node in a cluster directly. Since in our scheme, a deployment group can have 221 members including a group head (an H-sensor node), our scheme supports 22,000 regular sensor nodes. In LEKM, any single cluster head's capture could compromise the 100 sensors' secret keys. From this figure, we note that no matter how many cluster heads (group heads) are compromised in the network initialization phase, our scheme and IKDM provide perfect resilience against cluster head (group head) capture attack. However, in LEKM, as the number of compromising cluster heads increases the number of compromised sensor keys also increases. Thus, we see that our scheme as well as IKDM provide better security against cluster head (group head) capture attack as compared to that for LEKM during network initialization phase. But when the group heads are captured after network initialization phase, all the keys in sensors are compromised in case of LEKM and IKDM. Also, recently Paterson et al. [26] presented two attacks on IKDM. They showed that their attacks can result in the compromise

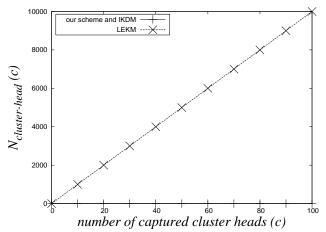


Fig. 8. Number of compromised regular sensor keys versus number of the compromised cluster heads (group heads) in the network initialization phase. Here $N_{cluster-head}(c)$ denotes the number of compromised keys in sensor nodes after capturing c cluster heads (group heads).

of most if not all of the sensor node keys after a small number of cluster heads are compromised. In our scheme, only the keys of neighboring sensors of a group head will be compromised. Thus, other sensors will be non-compromised even the group head is compromised. Hence, our scheme provides significantly better security against cluster heads (group heads) capture as compared to that for LEKM and IKDM.

VII. CONCLUSION

In this paper, we have proposed an energy-efficient probabilistic group-based key distribution scheme for a largescale heterogeneous wireless sensor network. Our scheme always guarantees that any two non-compromised nodes in a deployment group can communicate each other with 100% secrecy. Moreover, it provides significantly better security against sensor node capture as compared to that for the existing related schemes. Overall, we conclude that our scheme has a better trade-off among network connectivity, security, communication and computational overheads than the existing related schemes. In addition, our scheme supports dynamic regular sensor node addition as well as dynamic group head addition after initial deployment in the network.

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