

# JACOB'S LADDERS AND THE $\tilde{Z}^2$ -TRANSFORMATION OF THE ORTHOGONAL SYSTEM OF TRIGONOMETRIC FUNCTIONS

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ABSTRACT. It is shown in this paper that there is a continuum set of orthogonal systems relative to the weight function  $\tilde{Z}^2(t)$ . The corresponding integrals cannot be obtained in known theories of Balasubramanian, Heath-Brown and Ivic.

## 1. THE FIRST RESULT

1.1. In this paper we obtain some new properties of the signal

$$(1.1) \quad Z(t) = e^{i\vartheta(t)} \zeta\left(\frac{1}{2} + it\right)$$

that is generated by the Riemann zeta-function, where

$$(1.2) \quad \vartheta(t) = -\frac{t}{2} \ln \pi + \operatorname{Im} \ln \Gamma\left(\frac{1}{4} + i\frac{t}{2}\right) = \frac{t}{2} \ln \frac{t}{2\pi} - \frac{t}{2} - \frac{\pi}{8} + \mathcal{O}\left(\frac{1}{t}\right).$$

Let us remind that

$$(1.3) \quad \tilde{Z}^2(t) = \frac{d\varphi_1(t)}{dt}, \quad \varphi_1(t) = \frac{1}{2}\varphi(t)$$

where

$$(1.4) \quad \tilde{Z}^2(t) = \frac{Z^2(t)}{2\Phi_\varphi[\varphi(t)]} = \frac{Z^2(t)}{\left\{1 + \mathcal{O}\left(\frac{\ln \ln t}{\ln t}\right)\right\} \ln t}$$

(see [12], (5.1)-(5.3)) and  $\varphi_1(T)$ ,  $T \geq T_0[\varphi_1]$  is the Jacob's ladder.

1.2. It is known that the system of trigonometric functions

$$(1.5) \quad \left\{1, \cos\left(\frac{\pi}{l}t\right), \sin\left(\frac{\pi}{l}t\right), \dots, \cos\left(\frac{\pi}{l}nt\right), \sin\left(\frac{\pi}{l}nt\right), \dots\right\}$$

is the orthogonal system on the segment  $[0, 2l]$ . In this direction the following theorem holds true.

**Theorem 1.** Let  $\mathcal{J}(2l) = \varphi_1\{\mathring{\mathcal{J}}(2l)\}$ , where

$$\mathcal{J}(2l) = \mathcal{J}(2l, K) = [2lK, 2l(K+1)],$$

$$\mathring{\mathcal{J}}(2l) = \mathring{\mathcal{J}}(2l, K) = \left[ \widehat{2lK}, \widehat{2l(K+1)} \right], \quad 2lK \geq T_0[\varphi_1],$$

$$2l \in \left(0, \frac{T}{\ln T}\right]; \quad K \in \mathbb{N}.$$

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Then the system of functions

$$(1.6) \quad \left\{ 1, \cos\left(\frac{\pi}{l}\varphi_1(t)\right), \sin\left(\frac{\pi}{l}\varphi_1(t)\right), \dots, \cos\left(\frac{\pi}{l}n\varphi_1(t)\right), \sin\left(\frac{\pi}{l}n\varphi_1(t)\right), \dots \right\}$$

is the orthogonal system on  $\mathcal{J}(2l)$  with respect to the weight function  $\tilde{Z}^2(t)$ , i.e. the following new system of integrals

$$(1.7) \quad \begin{aligned} \int_{\mathcal{J}(2l)} \cos\left(\frac{\pi}{l}m\varphi_1(t)\right) \cos\left(\frac{\pi}{l}n\varphi_1(t)\right) \tilde{Z}^2(t)dt &= \begin{cases} 0 & , \quad m \neq n, \\ l & , \quad m = n, \end{cases} \\ \int_{\mathcal{J}(2l)} \sin\left(\frac{\pi}{l}m\varphi_1(t)\right) \sin\left(\frac{\pi}{l}n\varphi_1(t)\right) \tilde{Z}^2(t)dt &= \begin{cases} 0 & , \quad m \neq n, \\ l & , \quad m = n, \end{cases} \\ \int_{\mathcal{J}(2l)} \sin\left(\frac{\pi}{l}m\varphi_1(t)\right) \cos\left(\frac{\pi}{l}n\varphi_1(t)\right) \tilde{Z}^2(t)dt &= 0, \\ \int_{\mathcal{J}(2l)} \cos\left(\frac{\pi}{l}n\varphi_1(t)\right) \tilde{Z}^2(t)dt &= 0, \\ \int_{\mathcal{J}(2l)} \sin\left(\frac{\pi}{l}n\varphi_1(t)\right) \tilde{Z}^2(t)dt &= 0 \end{aligned}$$

for all  $m, n \in \mathbb{N}$  is obtained, where

$$(A) \quad t - \varphi_1(t) \sim (1 - c)\pi(t),$$

$$(B) \quad 2l(K + 1) < \overset{\circ}{2lK},$$

$$(C) \quad \rho\{\mathcal{J}(2l); \mathcal{J}(2l)\} \sim (1 - c)\pi(t) \rightarrow \infty,$$

as  $K \rightarrow \infty$ , and  $\rho$  denotes the distance of the corresponding segments,  $c$  is the Euler constant and  $\pi(t)$  is the prime-counting function.

*Remark 1.* Theorem 1 gives the contact point between the functions  $\zeta\left(\frac{1}{2} + it\right)$ ,  $\pi(t)$ ,  $\varphi_1(t)$  and the orthogonal system of trigonometric functions.

*Remark 2.* It is clear that the formulae (1.7) - for the modulated function  $\tilde{Z}^2(t)$  - cannot be obtained in the known theories of Balasubramanian, Heath-Brown and Ivic (comp. [1]).

This paper is a continuation of the series [2]-[15].

## 2. NEW METHOD OF THE QUANTIZATION OF THE HARDY-LITTLEWOOD INTEGRAL (A SPECIAL CASE)

2.1. We obtain from the first two formulae in (1.7)

$$(2.1) \quad \begin{aligned} \int_{\mathcal{J}(2l)} \cos^2\left(\frac{\pi}{l}m\varphi_1(t)\right) \tilde{Z}^2(t)dt &= \frac{1}{2}|\mathcal{J}(2l)|, \\ \int_{\mathcal{J}(2l)} \sin^2\left(\frac{\pi}{l}m\varphi_1(t)\right) \tilde{Z}^2(t)dt &= \frac{1}{2}|\mathcal{J}(2l)| \end{aligned}$$

for all  $m \in \mathbb{N}$ . Next, from (2.1) we obtain

**Corollary 1.**

$$(2.2) \quad \int_{\mathcal{J}(2l)} \tilde{Z}^2(t)dt = |\mathcal{J}(2l)|; \quad |\mathcal{J}(2l)| = 2l.$$

2.2. Let us consider now the problem concerning the solid of revolution corresponding to the graph of the function (comp. [5])

$$\tilde{Z}(t), t \in [\widehat{2lK}, +\infty), 2lK > T_0[\varphi_1].$$

**Problem.** To divide this solid of revolution on parts of equal volumes.

From (2.2) we obtain the resolution of this problem.

**Corollary 2.** Since

$$(a) \quad [\widehat{2lK}, +\infty) = \bigcup_{r=1}^{\infty} \mathring{\mathcal{J}}(2l, r), \quad \mathring{\mathcal{J}}(2l, r) = [\widehat{2l(K+r-1)}, \widehat{2l(K+r)}],$$

$$(b) \quad \pi \int_{\mathring{\mathcal{J}}(2l, r)} \tilde{Z}^2(t) dt = 2\pi l, \quad r = 1, 2, 3, \dots,$$

it follows that the sequence of points

$$\{\widehat{2l(K+r-1)}\}_{r=2}^{+\infty}$$

is the resolution to the Problem for arbitrary fixed  $2l \in (0, T/\ln T]$ .

### 3. GENERALIZATION OF THE FORMULA (2.2)

3.1. The following theorem holds true.

**Theorem 2.** Let

$$\mathcal{J}(T, U) = [T, T + U], \quad J(T, U) = \varphi_1\{\mathring{\mathcal{J}}(T, U)\}; \quad \mathring{\mathcal{J}}(T, U) = [\mathring{T}, \widehat{T+U}].$$

Then

$$(3.1) \quad \int_{\mathring{\mathcal{J}}(T, U)} \tilde{Z}^2(t) dt = |\mathcal{J}(T, U)| = U,$$

for every  $T \geq T_0[\varphi_1]$ ,  $U \in (0, T/\ln T]$ .

*Remark 3.* From (3.1) the general method for quantization of the Hardy-Littlewood integral follows (comp. Corollary 2:  $2lK \rightarrow \forall T \geq T_0[\varphi_1]$ ,  $\mathcal{J}(2l) \rightarrow \mathcal{J}(T, U)$ ).

Next, we obtain, using the mean-value theorem in (3.1)

**Corollary 3.**

$$(3.2) \quad \tilde{Z}^2(\xi) = \frac{|\mathcal{J}(T, U)|}{|\mathring{\mathcal{J}}(T, U)|}, \quad \xi \in \xi(\mathring{T}, \widehat{T+U}), \quad \tilde{Z}(\xi) \neq 0,$$

i.e.

$$\tilde{Z}^2(\xi) : 1 = |\mathcal{J}(T, U)| : |\mathring{\mathcal{J}}(T, U)|.$$

3.2. Let  $\{[T', T' + 1]\}$  stands for the continuum set of segments  $[T', T' + 1] \subset [T, T + T/\ln T]$ . Since

$$\frac{1}{|\mathring{\mathcal{J}}(T', 1)|} = \tilde{Z}^2(\xi), \quad \xi = \xi(T') \in (\mathring{T}', \widehat{T' + 1})$$

then by the Riemann-Siegel formula

$$Z(t) = 2 \sum_{n \leq \sqrt{\frac{t}{2\pi}}} \frac{1}{\sqrt{n}} \cos\{\vartheta(t) - t \ln n\} + \mathcal{O}(t^{-1/4})$$

we obtain (see (1.4))

**Corollary 4.**

$$(3.3) \quad \frac{1}{\sqrt{|\mathring{\mathcal{J}}(T', 1)|}} \sim \frac{2}{\sqrt{\ln \xi}} \left| \sum_{n \leq \sqrt{\frac{\xi}{2\pi}}} \frac{1}{\sqrt{n}} \cos\{\vartheta(\xi) - \xi \ln n\} + \mathcal{O}(\xi^{-1/4}) \right|$$

where  $\xi = \xi(T')$ .

*Remark 4.* The formula (3.3) describes the complicated oscillations of the value  $|\mathring{\mathcal{J}}(T', 1)|$  generated by the nonlinear transformation  $\mathcal{J}(T', 1) = \varphi_1\{\mathring{\mathcal{J}}(T', 1)\}$ .

#### 4. PROOF OF THEOREMS 1 AND 2

4.1. Let us remind that the following lemma is true (see [12], (5.1)-(5.3))

**Lemma.** For every integrable function (in the Lebesgue sense)  $f(x)$ ,  $x \in [\varphi_1(T), \varphi_1(T+U)]$  the following is true

$$(4.1) \quad \int_T^{T+U} f[\varphi_1(t)] \tilde{Z}^2(t) dt = \int_{\varphi_1(T)}^{\varphi_1(T+U)} f(x) dx, \quad U \in (0, T/\ln T),$$

where  $t - \varphi_1(t) \sim (1 - c)\pi(t)$ .

*Remark 5.* The formula (4.1) is true also in the case when the integral on the right-hand side of eq. (4.1) is convergent but not absolutely (in the Riemann sense).

4.2. If  $\varphi_1\{\widehat{[T, T+U]}\} = [T, T+U]$  then we obtain from (4.1) the following formula

$$(4.2) \quad \int_{\mathring{T}}^{\widehat{T+U}} f[\varphi_1(t)] \tilde{Z}^2(t) dt = \int_T^{T+U} f(x) dx, \quad U \in (0, T/\ln T).$$

Next, in the case  $[T, T+U] = [2lK, 2lK+2l] = \mathcal{J}(2l)$ , we have

$$(4.3) \quad \int_{\mathcal{J}(2l)} F(t) dt = \int_0^{2l} F(t) dt$$

for every (integrable)  $2l$ -periodic function  $F(t)$ . Then from the known formulae

$$\begin{aligned} \int_{\mathcal{J}(2l)} \cos\left(\frac{\pi}{l}m\varphi_1(t)\right) \cos\left(\frac{\pi}{l}n\varphi_1(t)\right) dt &= \begin{cases} 0 & , m \neq n, \\ l & , m = n, \end{cases} \\ \int_{\mathcal{J}(2l)} \sin\left(\frac{\pi}{l}m\varphi_1(t)\right) \sin\left(\frac{\pi}{l}n\varphi_1(t)\right) dt &= \begin{cases} 0 & , m \neq n, \\ l & , m = n, \end{cases} \\ \int_{\mathcal{J}(2l)} \sin\left(\frac{\pi}{l}m\varphi_1(t)\right) \cos\left(\frac{\pi}{l}n\varphi_1(t)\right) dt &= 0, \\ \int_{\mathcal{J}(2l)} \cos\left(\frac{\pi}{l}n\varphi_1(t)\right) dt = 0, \quad \int_{\mathcal{J}(2l)} \sin\left(\frac{\pi}{l}n\varphi_1(t)\right) dt &= 0, \quad m, n \in \mathbb{N}, \end{aligned}$$

by the  $\tilde{Z}^2$ -transformation (see (4.2), (4.3);  $[\overset{\circ}{T}, \widehat{T+U}] = \overset{\circ}{\mathcal{J}}(2l)$ ) the formulae (1.7) follow. The properties (B), (C) in Theorem 1 are identical with [13], (A1), (B1).

4.3. The formula (3.1) follows from (4.2) in the case  $f(x) \equiv 1$ .

### 5. ANOTHER TYPE OF THE ORTHOGONAL SYSTEMS

It follows from (4.2) that the continuum set  $\mathcal{S}(T, 2l)$  of the systems

$$\begin{aligned} &\left\{ |\tilde{Z}(t)|, |\tilde{Z}(t)| \cos\left(\frac{\pi}{l}(\varphi_1(t) - T)\right), |\tilde{Z}(t)| \sin\left(\frac{\pi}{l}(\varphi_1(t) - T)\right), \dots, \right. \\ &\left. |\tilde{Z}(t)| \cos\left(\frac{\pi}{l}n(\varphi_1(t) - T)\right), |\tilde{Z}(t)| \sin\left(\frac{\pi}{l}n(\varphi_1(t) - T)\right), \dots \right\}, \\ &t \in [\overset{\circ}{T}, \widehat{T+2l}] \end{aligned}$$

for all

$$T \geq T_0[\varphi_1], \quad 2l \in (0, T/\ln T]$$

is the set of orthogonal systems on  $[\overset{\circ}{T}, \widehat{T+2l}]$ .

*Remark 6.* Let us call the elements of the system  $\mathcal{S}(T, 2l)$  for fixed  $2l \in (0, T/\ln T]$  and for all  $T \geq T_0[\varphi_1]$  as *the clones* of the known orthogonal trigonometric system

$$\left\{ 1, \cos\left(\frac{\pi}{l}t\right), \sin\left(\frac{\pi}{l}t\right), \dots, \cos\left(\frac{\pi}{l}nt\right), \sin\left(\frac{\pi}{l}nt\right), \dots \right\}, \quad t \in [0, 2l].$$

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