# A Linear Equation of Motion

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#### Abstract

In classical mechanics, this paper presents a linear equation of motion, which can be applied in any reference frame (rotating or non-rotating) (inertial or non-inertial) without the necessity of introducing fictitious forces.

### **Linear Equation of Motion**

If we consider two particles A and B of mass  $m_a$  and  $m_b$  respectively, then the linear equation of motion, is given by:

$$m_a m_b \left[ \frac{(\mathbf{r}_a - \mathbf{r}_b)}{|\mathbf{r}_a - \mathbf{r}_b|} \cdot (\mathbf{v}_a - \mathbf{v}_b) \right] = m_a m_b \left[ \frac{(\mathbf{r}_a - \mathbf{r}_b)}{|\mathbf{r}_a - \mathbf{r}_b|} \cdot \int \left( \frac{\mathbf{F}_a}{m_a} - \frac{\mathbf{F}_b}{m_b} \right) dt \right]$$

where  $\mathbf{r}_a$  and  $\mathbf{r}_b$  are the positions of particles A and B,  $\mathbf{v}_a$  and  $\mathbf{v}_b$  are the velocities of particles A and B, and  $\mathbf{F}_a$  and  $\mathbf{F}_b$  are the net forces acting on particles A and B.

This linear equation of motion can be applied in any reference frame (rotating or non-rotating) (inertial or non-inertial) without the necessity of introducing fictitious forces. In addition, this linear equation of motion is invariant under transformations between reference frames.

## **Conservation of Linear Momentum**

A system of particles forms a system of biparticles. For example, the system of particles A, B, C and D forms the system of biparticles AB, AC, AD, BC, BD and CD.

The total linear momentum of a system of biparticles, is given by:

$$\sum_{i} \sum_{j>i} m_i m_j \left[ \frac{(\mathbf{r}_i - \mathbf{r}_j)}{|\mathbf{r}_i - \mathbf{r}_j|} \cdot (\mathbf{v}_i - \mathbf{v}_j) - \frac{(\mathbf{r}_i - \mathbf{r}_j)}{|\mathbf{r}_i - \mathbf{r}_j|} \cdot \int \left( \frac{\mathbf{F}_i}{m_i} - \frac{\mathbf{F}_j}{m_j} \right) dt \right] = 0$$

where  $m_i$  and  $m_j$  are the masses of the *i*-th and *j*-th particles,  $\mathbf{r}_i$  and  $\mathbf{r}_j$  are the positions of the *i*-th and *j*-th particles,  $\mathbf{v}_i$  and  $\mathbf{v}_j$  are the velocities of the *i*-th and *j*-th particles, and  $\mathbf{F}_i$  and  $\mathbf{F}_j$  are the net forces acting on the *i*-th and *j*-th particles.

Consequently, from the above equation it follows that the total linear momentum of a system of biparticles is always in equilibrium.

On the other hand, the above equation would be valid even if Newton's third law were false.

#### **General Equation of Motion**

The linear equation of motion can be obtained from the following general equation of motion:

$$\sum_{i} \sum_{j>i} m_i m_j \left[ \frac{(\mathbf{r}_i - \mathbf{r}_j)}{|\mathbf{r}_i - \mathbf{r}_j|} \cdot (\mathbf{r}_i - \mathbf{r}_j) - \frac{(\mathbf{r}_i - \mathbf{r}_j)}{|\mathbf{r}_i - \mathbf{r}_j|} \cdot \int \int \left( \frac{\mathbf{F}_i}{m_i} - \frac{\mathbf{F}_j}{m_j} \right) dt dt \right] = 0$$

where  $m_i$  and  $m_j$  are the masses of the *i*-th and *j*-th particles,  $\mathbf{r}_i$  and  $\mathbf{r}_j$  are the positions of the *i*-th and *j*-th particles, and  $\mathbf{F}_i$  and  $\mathbf{F}_j$  are the net forces acting on the *i*-th and *j*-th particles.