# A Linear Equation of Motion 

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#### Abstract

In classical mechanics, this paper presents a linear equation of motion, which can be applied in any reference frame (rotating or non-rotating) (inertial or non-inertial) without the necessity of introducing fictitious forces.


## Linear Equation of Motion

If we consider two particles A and B of mass $m_{a}$ and $m_{b}$ respectively, then the linear equation of motion, is given by:

$$
m_{a} m_{b}\left[\frac{\left(\mathbf{r}_{a}-\mathbf{r}_{b}\right)}{\left|\mathbf{r}_{a}-\mathbf{r}_{b}\right|} \cdot\left(\mathbf{v}_{a}-\mathbf{v}_{b}\right)\right]=m_{a} m_{b}\left[\frac{\left(\mathbf{r}_{a}-\mathbf{r}_{b}\right)}{\left|\mathbf{r}_{a}-\mathbf{r}_{b}\right|} \cdot \int\left(\frac{\mathbf{F}_{a}}{m_{a}}-\frac{\mathbf{F}_{b}}{m_{b}}\right) d t\right]
$$

where $\mathbf{r}_{a}$ and $\mathbf{r}_{b}$ are the positions of particles A and B, $\mathbf{v}_{a}$ and $\mathbf{v}_{b}$ are the velocities of particles A and B, and $\mathbf{F}_{a}$ and $\mathbf{F}_{b}$ are the net forces acting on particles A and B.

This linear equation of motion can be applied in any reference frame (rotating or non-rotating) (inertial or non-inertial) without the necessity of introducing fictitious forces. In addition, this linear equation of motion is invariant under transformations between reference frames.

## Conservation of Linear Momentum

A system of particles forms a system of biparticles. For example, the system of particles A, B, C and D forms the system of biparticles AB, AC, $\mathrm{AD}, \mathrm{BC}, \mathrm{BD}$ and CD .

The total linear momentum of a system of biparticles, is given by:

$$
\sum_{i} \sum_{j>i} m_{i} m_{j}\left[\frac{\left(\mathbf{r}_{i}-\mathbf{r}_{j}\right)}{\left|\mathbf{r}_{i}-\mathbf{r}_{j}\right|} \cdot\left(\mathbf{v}_{i}-\mathbf{v}_{j}\right)-\frac{\left(\mathbf{r}_{i}-\mathbf{r}_{j}\right)}{\left|\mathbf{r}_{i}-\mathbf{r}_{j}\right|} \cdot \int\left(\frac{\mathbf{F}_{i}}{m_{i}}-\frac{\mathbf{F}_{j}}{m_{j}}\right) d t\right]=0
$$

where $m_{i}$ and $m_{j}$ are the masses of the $i$-th and $j$-th particles, $\mathbf{r}_{i}$ and $\mathbf{r}_{j}$ are the positions of the $i$-th and $j$-th particles, $\mathbf{v}_{i}$ and $\mathbf{v}_{j}$ are the velocities of the $i$-th and $j$-th particles, and $\mathbf{F}_{i}$ and $\mathbf{F}_{j}$ are the net forces acting on the $i$-th and $j$-th particles.

Consequently, from the above equation it follows that the total linear momentum of a system of biparticles is always in equilibrium.

On the other hand, the above equation would be valid even if Newton's third law were false.

## General Equation of Motion

The linear equation of motion can be obtained from the following general equation of motion:

$$
\sum_{i} \sum_{j>i} m_{i} m_{j}\left[\frac{\left(\mathbf{r}_{i}-\mathbf{r}_{j}\right)}{\left|\mathbf{r}_{i}-\mathbf{r}_{j}\right|} \cdot\left(\mathbf{r}_{i}-\mathbf{r}_{j}\right)-\frac{\left(\mathbf{r}_{i}-\mathbf{r}_{j}\right)}{\left|\mathbf{r}_{i}-\mathbf{r}_{j}\right|} \cdot \iint\left(\frac{\mathbf{F}_{i}}{m_{i}}-\frac{\mathbf{F}_{j}}{m_{j}}\right) d t d t\right]=0
$$

where $m_{i}$ and $m_{j}$ are the masses of the $i$-th and $j$-th particles, $\mathbf{r}_{i}$ and $\mathbf{r}_{j}$ are the positions of the $i$-th and $j$-th particles, and $\mathbf{F}_{i}$ and $\mathbf{F}_{j}$ are the net forces acting on the $i$-th and $j$-th particles.

